

Rendering: Materials 1

Bernhard Kerbl

Research Division of Computer Graphics Institute of Visual Computing & Human-Centered Technology TU Wien, Austria



Today's Roadmap

Adding refractions

- Snell's Law
- Fresnel Reflectance
- Specular BTDF

- Important concepts
 - Chromatic Aberration
 - Heckbert Notation

Caustics



Today's Roadmap

- Adding refractions
 - Snell's Law
 - Fresnel Reflectance
 - Specular BTDF

- Important concepts
 - Chromatic Aberration
 - Heckbert Notation
 - Caustics





Physical (wave) optics:

- Derived using a detailed model of light
- Treating it as wave and computing solutions to Maxwell's equations
- Computationally expensive, usually not appreciably more accurate

Geometric optics:

- Requires surface's low-level scattering and geometric properties
- Closed-form reflection models derived from these properties
- More tractable, complex wave effects like polarization are ignored



The Missing Part of the Rendering Equation

$$L_e(x,v) = E(x,v) + \int_{\Omega} f_r(x,\omega \to v) L_i(x,\omega) \cos(\theta_x) d\omega$$

- Bidirectional Scattering Distribution Function (BSDF)
- Describes the light transport properties of the material
- So far, we only implemented simple diffuse surface reflections
- Can model reflections, refractions, volumetric scattering...



Bidirectional Reflectance Distribution Function (BRDF)



- Considers only the **reflection** of incoming light onto a surface
 - The BRDF is a limited instance of the full BSDF (e.g., no transparency)
 - Good for starting out, complex materials need full BSDF
 - More on that in another lecture

- A BRDF function $f_r(x, \omega_i \to \omega_o)$ with input directions ω_i, ω_o
 - uses convention: ω_i and ω_o are assumed to point away from x
 - How much irradiance from ω_i is reflected as radiance to ω_o at x?





• "How much irradiance from ω_i is reflected as radiance to ω_o at x?"

$$f_{r}(x,\omega_{i} \to \omega_{o}) = \frac{dL_{i}(x,\omega_{o})}{dE_{i}(x,\omega_{i})} = \frac{dL_{i}(x,\omega_{o})}{L_{i}(x,\omega_{i})\cos\theta(\omega_{i})d\omega_{i}}$$
$$L_{e}(x,v) = E(x,v) + \int_{\Omega} f_{r}(x,\omega \to v)L_{i}(x,\omega)\cos(\theta_{x})d\omega$$

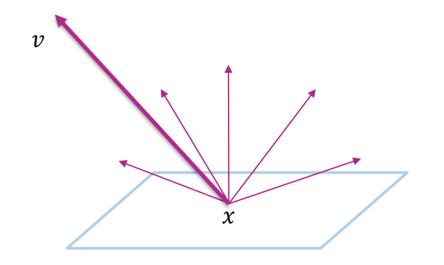
• Helmholtz reciprocity: $f_r(x, \omega_i \to \omega_o) = f_r(x, \omega_o \to \omega_i)$

Conserves energy:
$$\int_{\Omega} f_r(x, \omega \to v) \cos \theta \, d\omega \le 1 \, \forall \, v$$





- Why must the BRDF f_r fulfill $\int_{\Omega} f_r(x, \omega \to v) \cos_{\theta}(\omega) d\omega \le 1$?
- Intuitive interpretation with **reciprocity**: Shine a laser light along -v onto x. We must have $\int_{\Omega} f_r(x, v \to \omega) \cos_{\theta}(\omega) d\omega \leq 1$
- If we find a direction v for which this is not true, it means we would reflect more light than is coming in

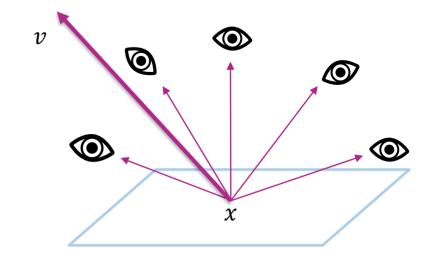






• Why must the BRDF f_r fulfill $\int_{\Omega} f_r(x, \omega \to v) \cos_{\theta}(\omega) d\omega \le 1$?

- Intuitive interpretation with **reciprocity**: Shine a laser light along -v onto x. We must have $\int_{\Omega} f_r(x, v \to \omega) \cos_{\theta}(\omega) d\omega \leq 1$
- If we find a direction v for which this is not true, it means we would reflect more light than is coming in



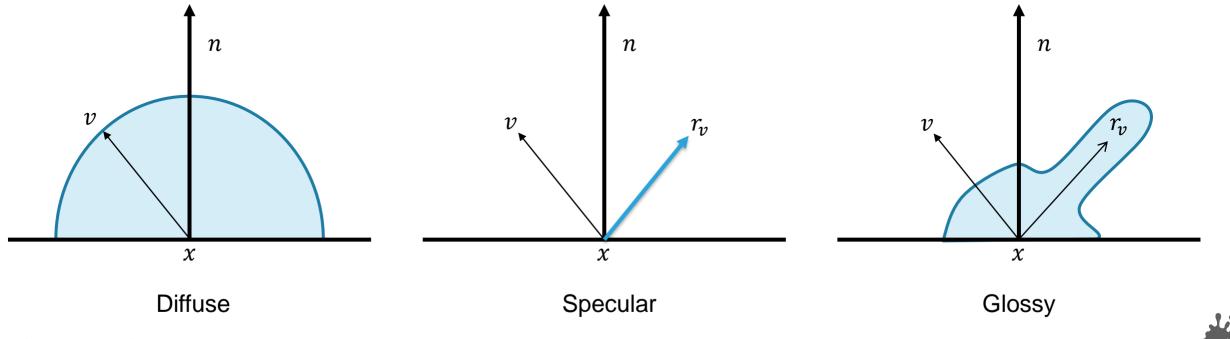


BRDF Types



We usually distinguish three basic BRDF types

- Perfectly diffuse (light is scattered equally in/from all directions)
- Perfectly specular (light is reflected in/from exactly one direction)
- Glossy (mixture of the other two, stronger reflectance around r_v)



BRDF Types



We usually distinguish three basic BRDF types

- Perfectly diffuse (light is scattered equally in/from all directions)
- Perfectly specular (light is reflected in/from exactly one direction)
- Glossy (mixture of the other two, stronger reflectance around r_v)





Before, we considered the BRDF value and sampling of ω separately

- For implementation, it makes a lot of sense to combine them
 - $f_r(x, \omega \rightarrow v)$ depends only on x, v and next ray direction ω
 - Rendering equation: we can't predict L_i , but $f_r(x, \omega \rightarrow v)$ and $\cos \theta$
 - Our renderings will converge faster if the distribution of ω actually matches the shape of $f_r(x, \omega \to v) \cos \theta$ (importance sampling!)
 - If we put the BRDF in charge of choosing our ω , we can make it sample a distribution that directly matches $f_r(x, \omega \to v) \cos \theta$

12

This actually makes things cleaner in code



Diffuse materials reflect same amount of light in/from all directions

Importance sampling $f_r(x, \omega \to v) \cos \theta \rightarrow use p(\omega) \propto \frac{\rho \cos \theta}{\pi}$

• Making it a valid PDF leads to $p(\omega) = \frac{\cos \theta}{\pi}$

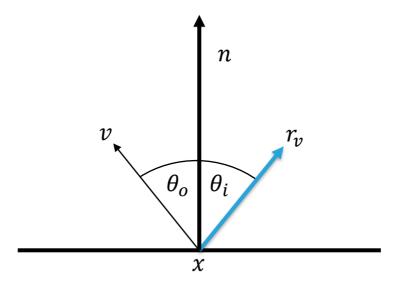
From previous exercise: it's cosine-weighted hemisphere sampling!





The angle of exiting light θ_o is the same as the angle of incidence θ_i

Incoming light is only transported in a single direction

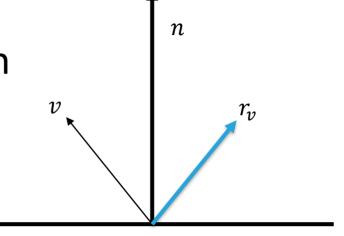


Specular



For purely specular BRDFs (a perfect mirror surface), irradiance from the perfect mirror direction r_v is completely reflected to v

 Irradiance coming from any other direction does not reflect at all towards v



$$f_r(x, \omega \to v) > 0 \Leftrightarrow \omega = r_v$$

Problem: if we pick the next direction ω randomly as before, the chances of ever hitting r_v by accident are infinitely small!





Model specular reflection with the Dirac delta function

Delta function $\delta(x)$ is defined to be 0 everywhere except at x = 0

• Use a shifted version $\delta_v(\omega)$ that is 0 everywhere except at $\omega = r_v$

Per definition, $\int_{\Omega} \delta_{v}(\omega) \, d\omega = 1$ to obtain a valid PDF for sampling

Ponder this for a moment: what value does $\delta_v(r_v)$ have?



Energy-Preserving Specular BRDF



Full energy preservation:
$$\int_{\Omega} f_r(x, \omega \to v) L_i \cos_{\theta}(\omega) d\omega = L_{r_v}$$

If we integrate using $f_r(x, \omega \to v) = \delta_v(\omega)$, we get $L_{r_v} \cos_{\theta}(r_v)$

We lost some light! We compensate:
$$f_r(x, \omega \to v) = \frac{\delta_v(\omega)}{\cos_\theta(r_v)}$$

If we consider the properties of the Dirac delta function, we can try to derive the same methods that we used before for diffuse BRDFs





sample(v**)**: mirror v about n (invert v_x , v_y in *local space*) and return

pdf(
$$\omega$$
): 0 if $\omega \neq r_v$, else: $\delta_v(r_v) = \infty$

But, if $\omega = r_v$, evaluate(v, ω) / pdf(ω) = $\frac{\delta_v(\omega)}{\delta_v(\omega)\cos_\theta(r_v)} = \frac{1}{\cos_\theta(r_v)}$



Revising the Specular BRDF Implementation



- **sample(**v**)**: mirror v about n (invert v_x , v_y in *local space*)
 - Return r_v as generated sample direction
 - Return multiplier for L_i as 1 (full radiance passed on)

No other function except **sample** should be able to just *guess* r_v

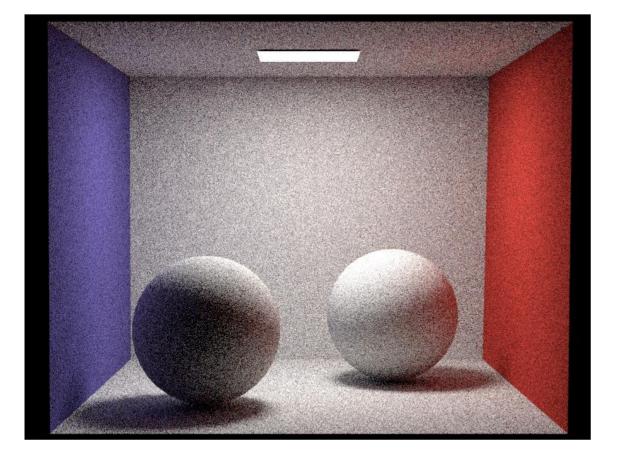
evaluate(a, b): always return 0

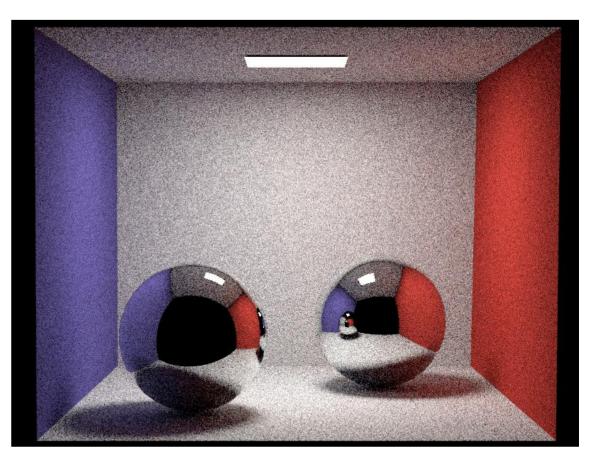
```
pdf(\omega): always return 0
```



Diffuse vs Specular in Action









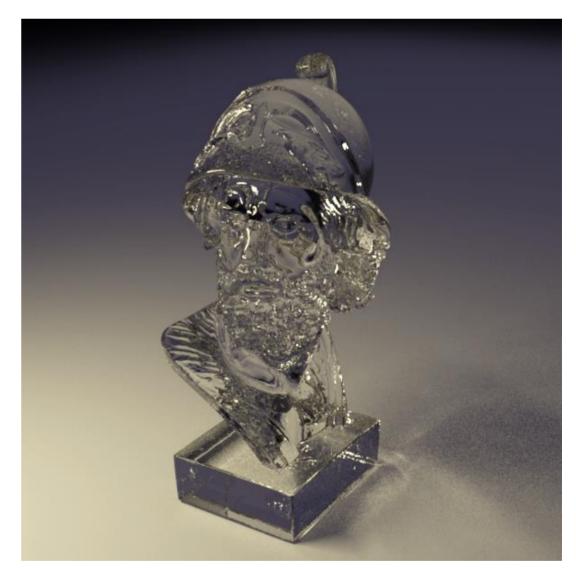
- Before, we assumed that the entire radiance is reflected (mirror)
- This is usually not the case
 - Some light is reflected on the surface
 - Some enters the new material (scattered, absorbed or **refracted**)
 - Meeting point of two different media is called interface
- When entering a different medium, light often changes direction
- Governed by the materials' index of refraction and Snell's law



Specular Reflection and Transmission







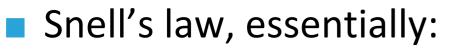


Snell's Law

Based on the indices of refraction for the two materials

- η_i for the medium that the light ray is currently in
- η_t for the new medium into which light is transmitted

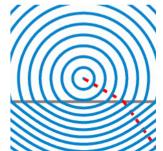
Index of refraction: how fast light travels in medium



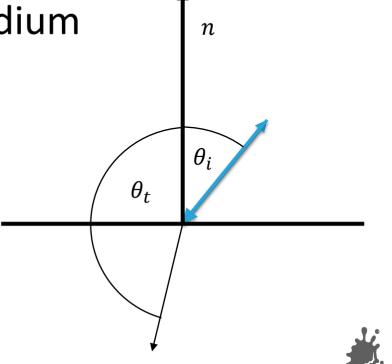
$$\eta_i \sin \theta_i = \eta_t \sin \theta_t$$

Given η_i , θ_i and η_t , we can easily solve for θ_t

Rendering – Materials



Public domain, <u>Oleg Alexandrov</u>, Snell's law wavefrons, Wikipedia, "Snell's law"







How much of the light do we reflect?

Not constant, but actually depends on the θ_i

The larger θ_i , the better the chance for reflection

If $\eta_i > \eta_t$, if incident light exceeds a certain θ_i , all light may be reflected (*total internal reflection*)







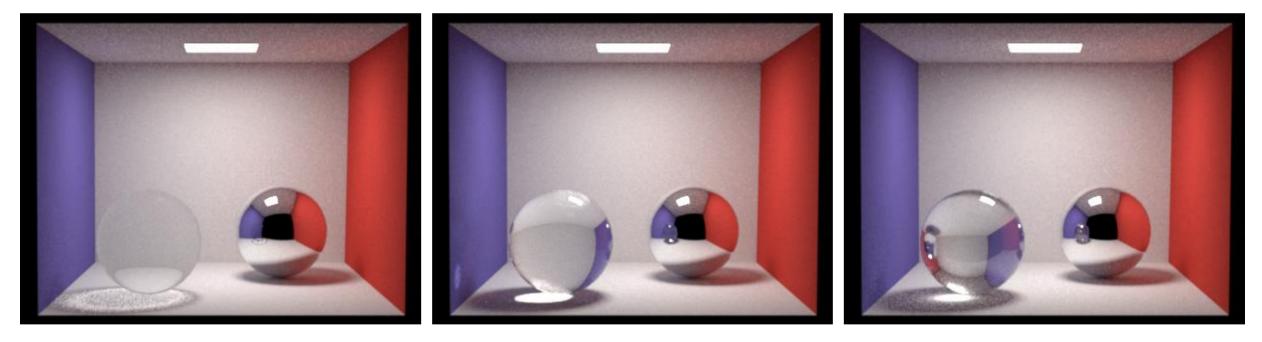
- Should be handled differently, depending on the materials involved
- Distinguish how material responds to energy transported by light
- We usually consider three major groups:
 - Dielectrics conduct electricity poorly (glass, air...)
 - Conductors (*metals*, reflect a lot, transmitted light quickly absorbed)
 - Semiconductors (complex, but also rare we can ignore them)

Remember, we are aiming for dielectrics today



Examples for the Index of Refraction in Dielectrics





 $\eta_t = 1.025$ (liquid helium)

 $\eta_t = 1.5$ (glass)

 $\eta_t = 2.5$ (diamond)

- Gases: 1 1.0005 (no-man's land from 1.05 to 1.25)
- Liquids: 1.3 (water) 1.5 (olive oil)
- Solids: 1.3 (ice) 2.5 (diamond)





Defined for parallel and perpendicular polarized light (r_{\parallel} and r_{\perp}):

$$r_{\parallel} = \frac{\eta_t \cos \theta_i - \eta_i \cos \theta_t}{\eta_t \cos \theta_i + \eta_i \cos \theta_t}, r_{\perp} = \frac{\eta_i \cos \theta_i - \eta_t \cos \theta_t}{\eta_i \cos \theta_i + \eta_t \cos \theta_t}$$

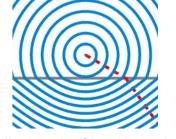
Amount of **reflected** light (unpolarized light, average of squares): $F_r = \frac{1}{2}(r_{\parallel}^2 + r_{\perp}^2)$

Amount of **refracted** light (conservation of energy): $1 - F_r$



Bidirectional Transmittance Distribution Function (BTDF)

- Refracted light usually changes direction in new medium
 - Remember that we work with radiance: $d\Phi = L_i dA_\perp d\omega$
 - Refracted light changes direction \rightarrow influences radiance!
 - Relate incoming to refracted light:



Public domain, <u>Oleg Alexandrov</u>, Snell's law wavefrons, Wikipedia, "Snell's law"

- $L_o \cos \theta_o \, dA \sin \theta_o \, d\theta_o \, d\phi_o = (1 F_r) L_i \cos \theta_i \, dA \sin \theta_i \, d\theta_i \, d\phi_i$
- Differentiating Snell's law w.r.t. θ , we get:

$$\eta_o \cos \theta_o \, d\theta_o = \eta_i \cos \theta_i \, d\theta_i \to \frac{\cos \theta_o d\theta_o}{\cos \theta_i d\theta_i} = \frac{\eta_i}{\eta_o}$$



Bidirectional Transmittance Distribution Function (BTDF)

Substituting, we get:

$$L_{o}\eta_{i}^{2}d\phi_{o} = (1 - F_{r})L_{i}\eta_{o}^{2} d\phi_{i} \to L_{o} = (1 - F_{r})\frac{\eta_{o}^{2}}{\eta_{i}^{2}}L_{i}$$

• We have all the required information for the specular BTDF!

- Use $T(\omega, n)$ to compute direction of ω when refracted at interface
- Like specular BRDF, light only goes in a single direction
- Can reuse BRDF $\delta(\omega)$ and normalization (similar implementation!)

$$f_r(x,\omega_i \to \omega_o) = \frac{\eta_o^2}{\eta_i^2} (1-F_r) \frac{\delta(\omega_i - T(\omega_o, n))}{|\cos \theta_i|}$$



Bidirectional Transmittance Distribution Function (BTDF)

- TU
- When light refracts into a material with a higher η , the energy is compressed into a smaller set of angles

- For the BTDF, $f_r(x, \omega_i \to \omega_o) = f_r(x, \omega_o \to \omega_i)$ is not guaranteed
- No reciprocity, but $\eta_i^2 f_r(x, \omega_i \to \omega_o) = \eta_o^2 f_r(x, \omega_o \to \omega_i)$ holds!

If you follow a view ray, do the same computations as above, just:

- Make sure you choose η_i for medium ray comes from
- Make sure you choose η_t for medium ray goes to





- I Just continue one path, use Fresnel to decide \rightarrow reflect or refract?
- View ray behaves exactly like **incident light** in the above equations
- You may find it easier to flip the normal if light exits a medium
 - Light that enters e.g. a glass body must also exit at some point
 - I.e., the incoming light ray is not in same hemisphere as n
 - Consistent with using η_i and η_t for current/new medium

Solving for θ_t , you may get "sin $\theta_t > 1$ " \rightarrow total internal reflection



Today's Roadmap

Adding refractions

- Snell's Law
- Fresnel Reflectance
- Specular BTDF

- Important concepts
 - Chromatic Aberration
 - Heckbert Notation
 - Caustics



Chromatic Aberration

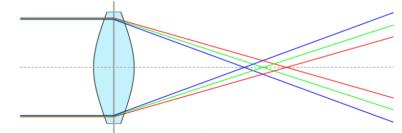


Physically speaking, the change in direction is wavelength-dependent

For proper simulation, would have to at least bend R/G/B differently

Would spawn two additional rays!

 Can of course be done, but is often ignored (tiny effect on most images)



Public domain, <u>Andreas 06</u>, Chromatic aberration convex, Wikipedia, "Chromatic aberration"



<u>CC BY-SA 3.0</u>, Stan Zurek, Chromatic aberration (comparison), Wikipedia, "Chromatic aberration"



Assign a letter to every interaction of a light path from light to eye

- L light
- D diffuse surface
- S specular surface
- E eye

Use regex to describe specific (e.g., very challenging) path types

- LE: direct path from light to eye
- L(D|S)*E: any path from light to eye
- LDS+E: a path with one diffuse bounce, followed by specular bounces

A Quick Word on Caustics



General: focused light from interacting with curved, specular surface



<u>CC BY-SA 3.0</u>, Heiner Otterstedt, Kaustik, Wikipedia, "Caustic (optics)"

<u>CC BY-SA 4.0, Markus Selmke</u>, Computer rendering of a wine glass caustic, Wikipedia, "Caustic (optics)"

For us, who are concerned with rendering and path tracing: LS+DE

Usually challenging to render (takes extremely long to converge)





SIGGRAPH University - Introduction to "Physically Based Shading in Theory and Practice" by Naty Hoffman (!!!)

 SIGGRAPH University - Recent Advances in Physically Based Shading by Naty Hoffman (advanced, in the same video there are also some other talks)



References and Further Reading

- Material for Dielectrics largely based on "Physically Based Rendering" book, chapter 8: Reflection Models
- [1] <u>Physically Based Rendering</u> (course book, chapters 8 and 9 for materials, chapter 11 for volume rendering)
- [2] <u>Background: Physics and Math of Shading</u> by Naty Hoffman
- [3] Wojciech Jarosz, "Efficient Monte Carlo Methods for Light Transport in Scattering Media", PhD Thesis, <u>https://cs.dartmouth.edu/~wjarosz/publications/dissertation/</u>
- [4] <u>Production Volume Rendering</u> (SIGGRAPH 2017 Course)
- [5] Monte Carlo methods for physically based volume rendering (SIGGRAPH 2018 Course)

